

**PARUL UNIVERSITY**  
**FACULTY OF ENGINEERING & TECHNOLOGY**  
**B.Tech. Winter 2019-20 Examination**

**Semester: 5**  
**Subject Code: 03112330**  
**Subject Name: Industrial Drives and Control**

**Date: 28/11/2019**  
**Time: 10:30 am to 01:00pm**  
**Total Marks: 60**

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**Instructions:**

1. All questions are compulsory.
2. Figures to the right indicate full marks.
3. Make suitable assumptions wherever necessary.
4. Start new question on new page.

**Q.1 Objective Type Questions****(15)**

1. Define Electric Drives
2. Define Dry friction load.
3. Define Fan type load.
4. Define efficiency.
5. What is stepper motor?
6. Which part of a motor needs maximum attention for maintenance?
  - A. Frame
  - B. Rearing
  - C. Stator Winding
  - D. Rotor Winding
7. During braking, to save energy \_\_\_\_\_ braking is used?
  - A. dynamic
  - B. plugging
  - C. regenerative
  - D. all of the above
8. Full form of VVVF control
  - A. variable voltage VAr frequency.
  - B. VAr variable voltage frequency.
  - C. variable VAr voltage frequency.
  - D. variable voltage variable frequency.
9. The basic elements of a electric drive are
  - A. electric motor.
  - B. control system.
  - C. electrical motor and control system.
  - D. none of the above.
10. A four quadrant operation requires
  - A. two full converters in series.
  - B. two full converters connected in parallel.
  - C. two full converter connected in back to back.
  - D. two semi converters connected in back to back

11. In 4 quadrant operation of a hoist 3rd quadrant represents\_\_\_\_\_.
12. \_\_\_\_\_ motor is a constant speed motor.
13. Write the function of power modulator.
14. The power modulator which is used to convert fixed DC voltage to variable DC voltage \_\_\_\_\_.
15. Define Self excited dc motor.

**Q.2** Answer the following questions. (Attempt any three) **(15)**

- A) Draw quadrant diagram of speed-torque characteristics.
- B) Draw and explain series and shunt DC motor.
- C) Define principle of chopper and explain class-A chopper.
- D) Draw and explain basic block diagram of closed loop control system.

**Q.3** A) “DC motor speed can be controlled by armature voltage, field current and armature resistance” **(07)**

Justify this statement with neat sketch and equation.

- B) The speed of a 10 hp, 230 V, 1200 rpm separately excited dc motor is controlled by a single phase **(08)**  
full converter. The rated armature current is 38A, armature resistance is  $0.3\Omega$ . The ac supply is 260V. The motor voltage constant is  $K_a\phi=0.182$  V/rpm. Find out i) motor torque ii) Speed of the motor iii) Supply power factor

**OR**

- B) Develop transfer function of motor for separately excited dc motor with functional block diagram **(08)**  
and derive equation.

**Q.4** A) Configure step up chopper derive output voltage equation for step up chopper. **(07)**

**OR**

- A) A series-connected DC motor has an armature resistance of  $0.5\Omega$  and field winding resistance of **(07)**  
 $1.5\Omega$ . In driving a certain load at 1200 rpm, the current drawn by the motor is 20A from a voltage source of  $V_T = 220V$ . The rotational loss is 150W. Find the output power and efficiency.

- B) Draw and explain 3- phase semi converter with wave forms. **(08)**